RUTLAND

Enhancing **compliance**
and **performance** at every door

Automatic Door Closer for swing doors

Fitting Instruction

rutlanduk.co.uk



- Warning – moving door. Risk of crushing and shearing at the hinge (secondary) edge and impact/crushing at the leading (main) edge. Keep the swing path clear during operation. Isolate the mains supply before any installation, adjustment or maintenance. Only competent, trained personnel may install, commission or service this product.
- Installation of automatic door should be entrusted to the appointed distributor or professional installation personnel.
- According to the laws and regulations on electrical construction, installation must be carried out by professionals.
- This manual must be kept well for maintenance.

Manufacturer:

Rutland, Unit 4 Holmewood Business Park, Chesterfield Road, Chesterfield, S42 5US, United Kingdom. This product is CE marked.

A Declaration of Conformity to Machinery Directive 2006/42/EC and EMC Directive 2014/30/EU has been issued by Rutland and is available on request.

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REV: 02B
DATE: OCT 2026

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AUTOMATIC DOOR CLOSER FOR SWING DOORS

Product Introduction

Product Information

"The AO.SD3 is a powered operator for internal/external pedestrian swing doors (leaf 700–1400 mm, max 350 kg). It must not be used for any other purpose, on doors outside these limits, or on a fire/smoke doorset that does not have valid fire test evidence for that doorset (see Other information). Do not modify the unit or defeat its safety sensors.

- Application : Timber door, steel door and composite door
- Adjustable performance: 35 parameters are adjustable.
- Door Width: 700mm - 1400mm
- Door weightL Max 350kg (Fig. 1)
- Door opening angle: 45°- 105°
- Fitting direction: Pull and Push
- Voltage: AC 220V (±10%) / AC 110V (±10%)
- Open mode: Sensors, Remotes, Keypad, etv.
- Working life: Over 2 million times.

Product Features



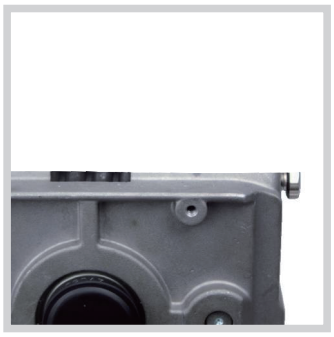
Automatic/Manual/Full open
3 modes switch



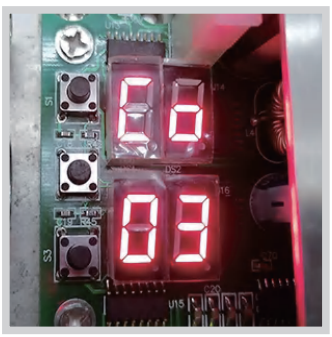
Spline shaft design
Strong connection



3 Types extension
Meet different installation space.



Built-in spring design
Work as door closer,
when no power.



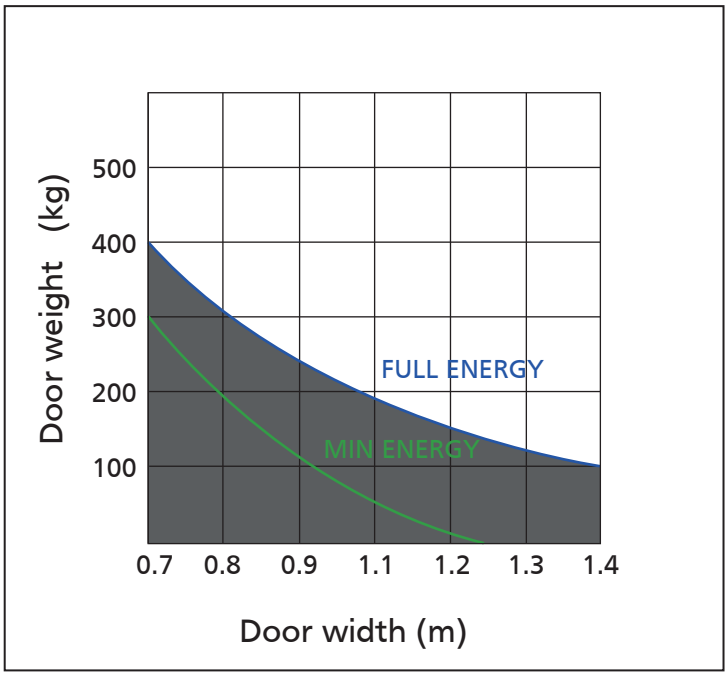
LED display， Easy operation



Low energy mode,providing
disabled access solution.

Technical Parameters

Size	610 x 90 x 128mm (W x H x D)
Voltage	110V/220V
Power	Standby 13W, rated 87W
Maximum Torque	50Nm
Opening Angle	45º - 105º (Adjustable)
Delay Time	0 - 30s (Adjustable)
Opening Speed	3 - 9s (Adjustable)
Closing Speed	3 - 9s (Adjustable)
Noise	18dB (Tested in 1m distance)
Max Weight	350kg



(Fig 1)

Standard/Optional Accessories

Product Code	Re-order code	Description
AO.SD3	**12798**	Rutland Swing Door Automatic Operator with Pull Bar Slide Arm
AO.SD3.EXT55	**12804**	Automatic Swing Door Closer with Pull Bar Slide Arm Extension - 55mm
AO.SD3.EXT85	**12805**	Automatic Swing Door Closer with Pull Bar Slide Arm Extension - 85mm
AO.IRSS.700	**12799**	Infrared safety top scan sensor - 700mm
AO.RFG.1925	**1XXXX**	Roller Finger Guard FP60 1925 Metal SAA and Black Fabric
AO.KEYPAD	**12800**	Rutland Access Keypad
AO.CARD	**12801**	ID Card for access control
AO.FOB	**12802**	ID key chain button
AO.REC	**12804**	Automatic door function remotes
AO.SDLink	**12804**	Link module for double door

Core Product



AO.SD3

Optional Accessories



AO.SD3.PUSH ARM



AO.IRSS.700



AO.SD3.EXT55



AO.SD3.EXT85



Electromagnetic Lock



AO.FOB



AO.CARD



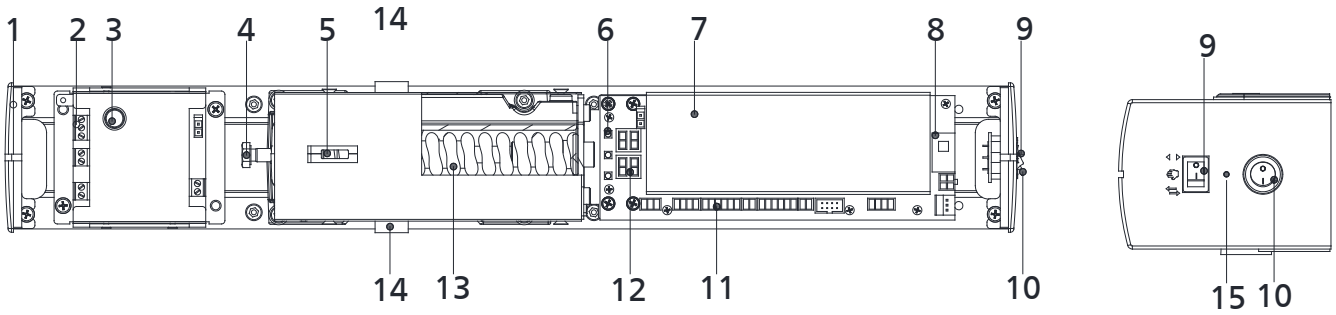
AO.KEYPAD



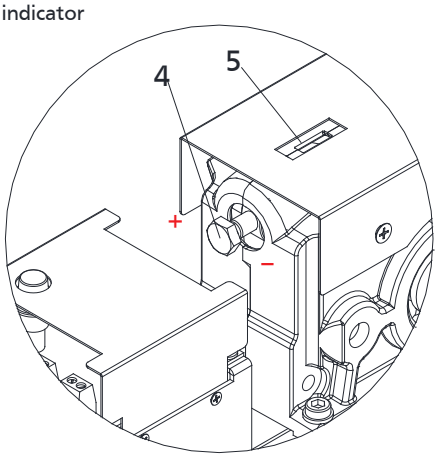
RAL900

Product Introduction





1.Side cover
2.Power input
3.Fuse
4.Spring force adjustment screw
5. Windows
6.Parameter adjustment button
7.Controller
8.Push / pull arm selection switch
9. Mode switch
10.Power switch
11.Wiring terminal
12.LED display
13.Spring
14.Motor output shaft
15.Power indicator



9. Mode switch:

Hold open mode: The door will remain open at this mode.

Manual mode: The door open manually, and close automatically.
All sensors can't work.

Automatic mode: The door work automatically, all sensors can work.

The spring force is different according to the width of the door leaf, so the spring force needs to be adjusted. The specific adjustment can be based on different door width. When adjusting, the wind pressure and overpressure / low pressure should also be fully considered (The door must be automatically closed in place when the power is turned off). The factory settings of the operator is the minimum spring force, which is suitable for the width of the 750mm-900mm

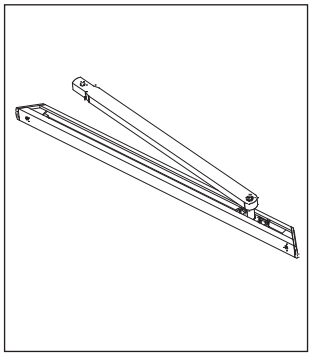
Adjust the screw clockwise to increase the spring force;counter clockwise to decrease force. Improper spring force may cause failure operation.

AUTOMATIC DOOR CLOSER FOR SWING DOORS

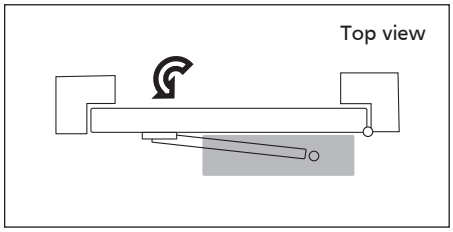
Pull/Push Arm Selection

Pull arm

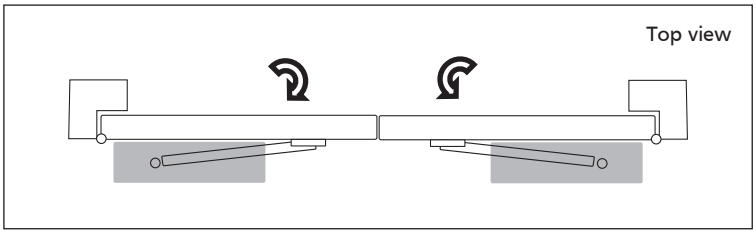








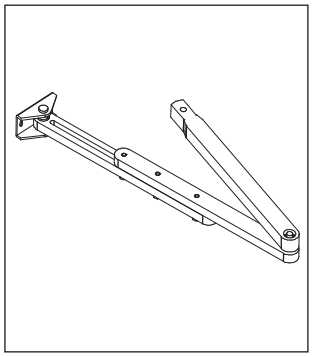
Single open

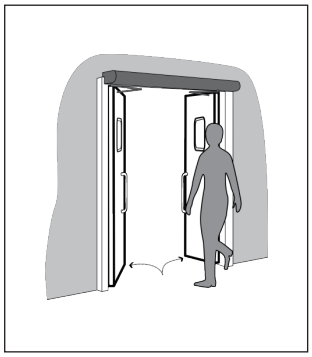


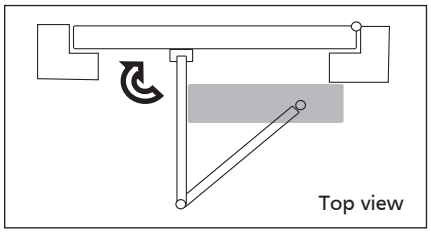
Double open

Push arm

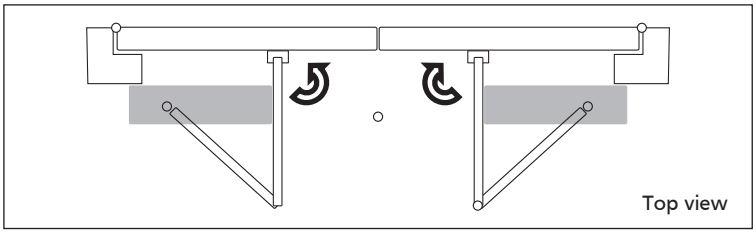








Single open

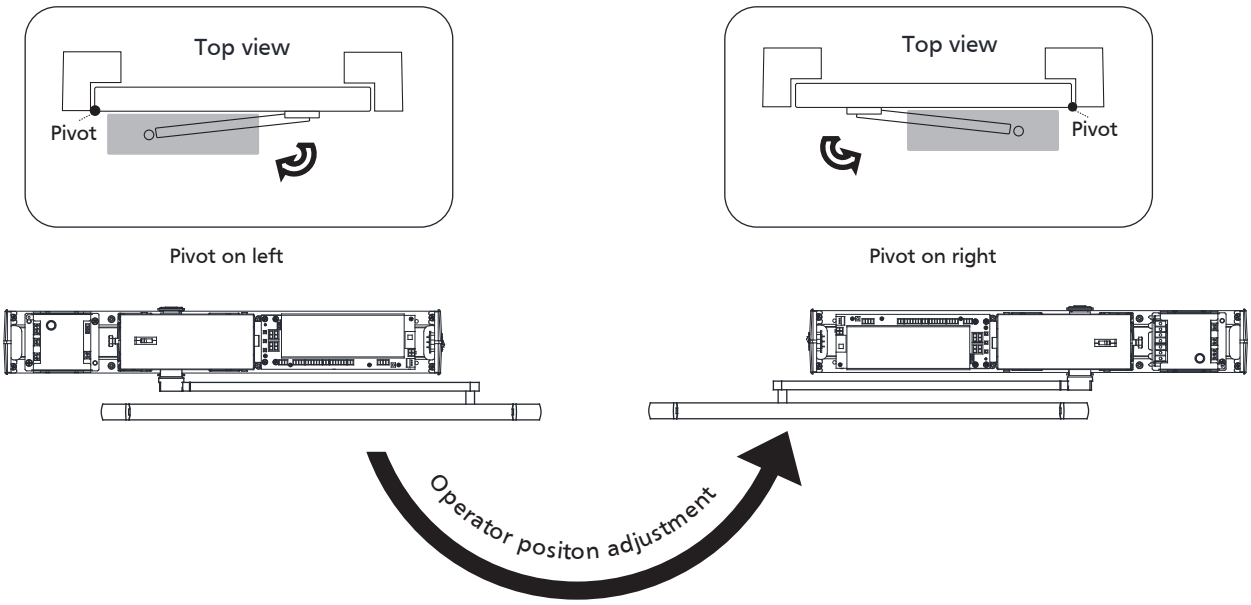


Double open

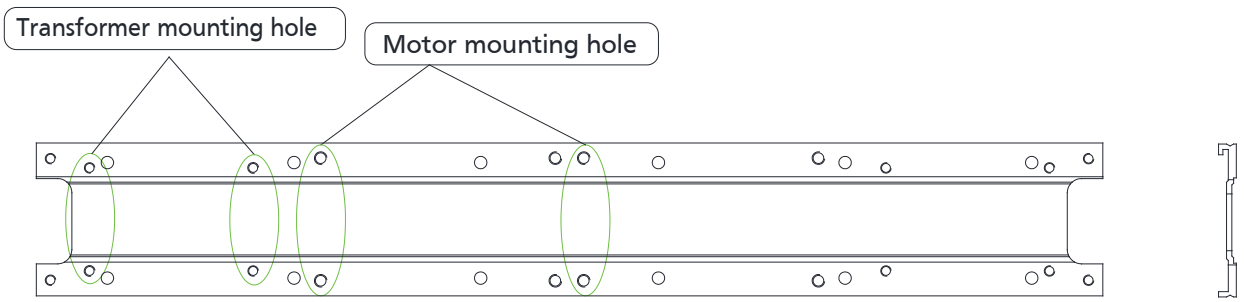
Installation Direction

Direction of operator installation

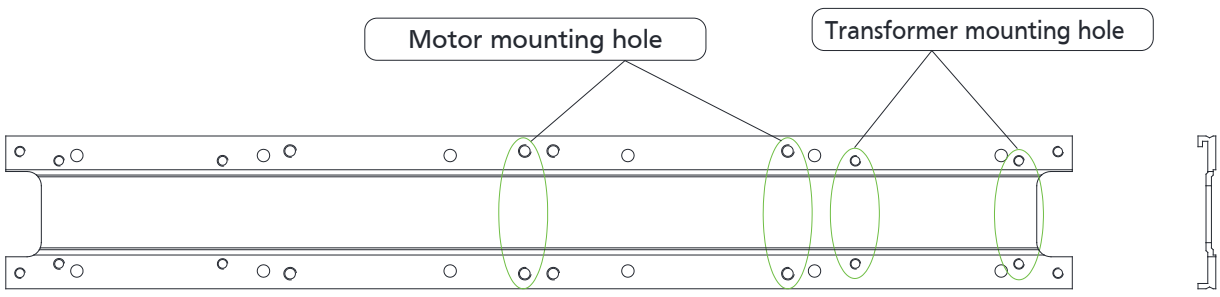
Factory default is left open. If it is Right open, you need to remove the motor, transformer and side cover by yourselves and rotate them by 180° and reassemble them.



Install on the left

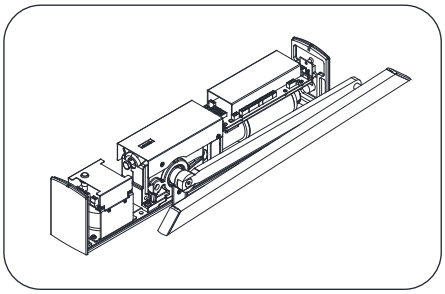


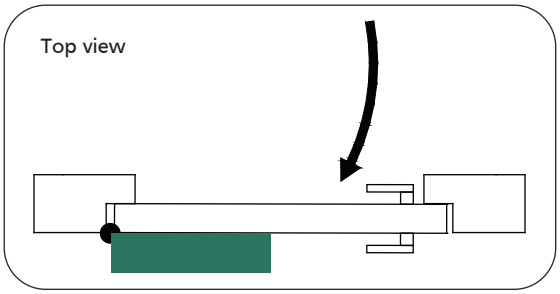
Install on the right

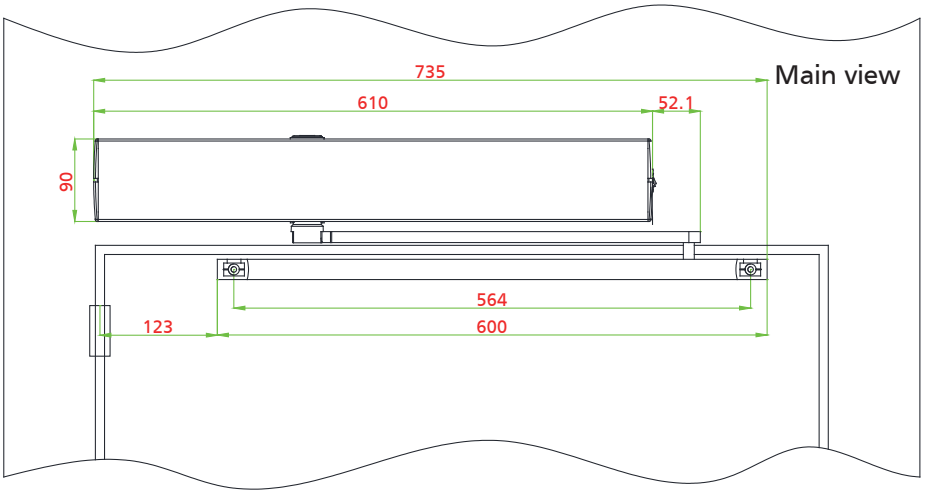


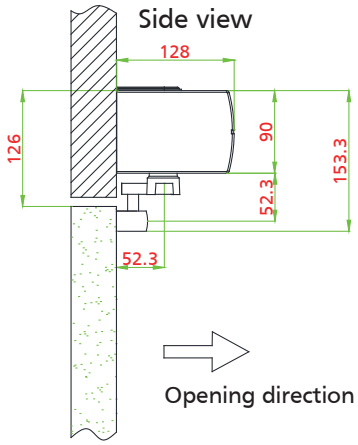
Installation (Pull Arm)

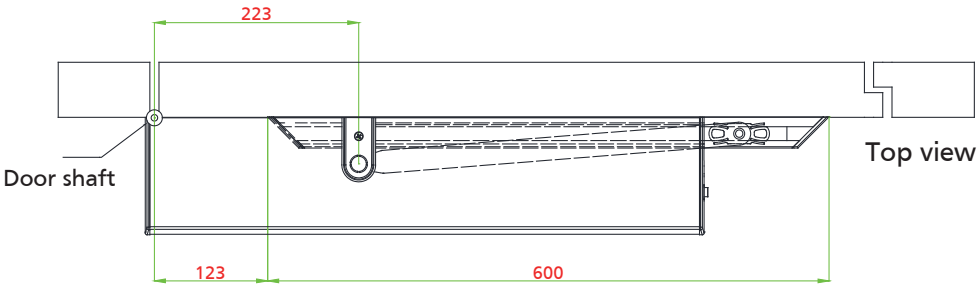
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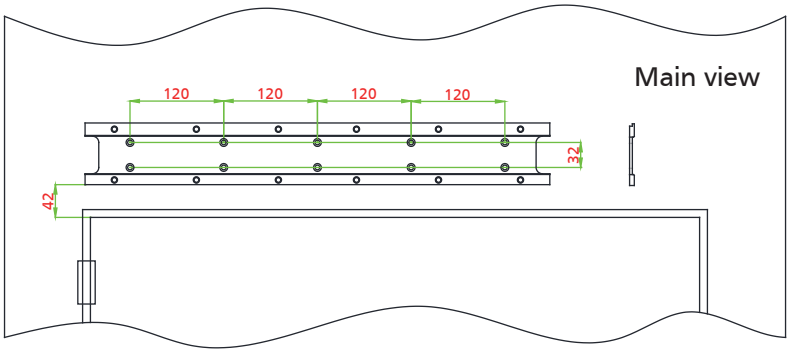




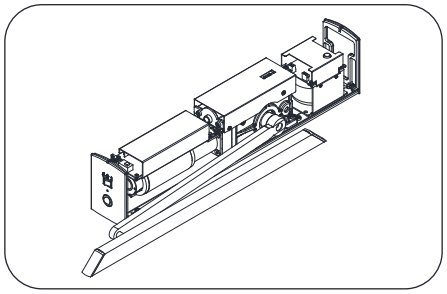


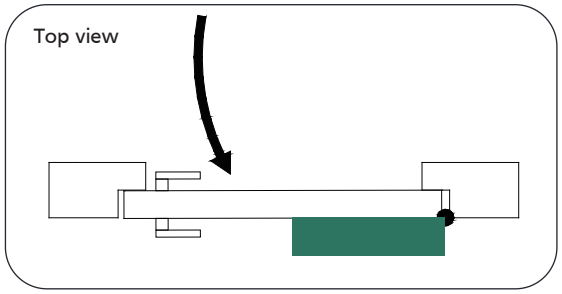


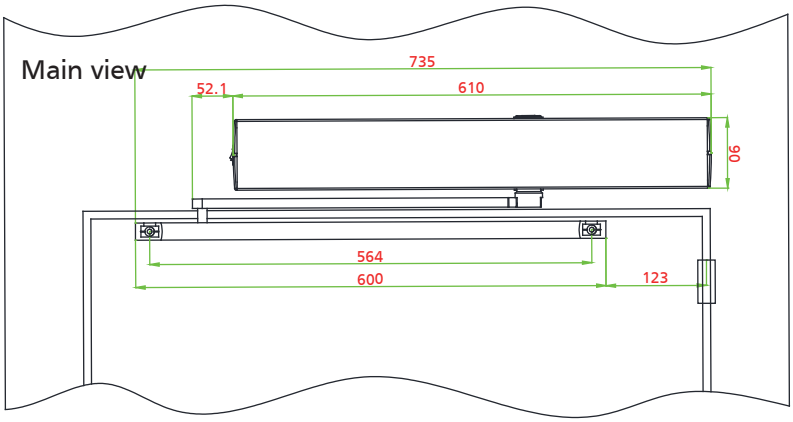
Bottom plate installation

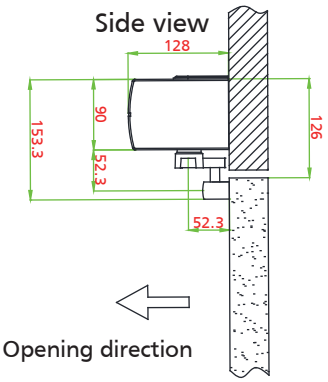


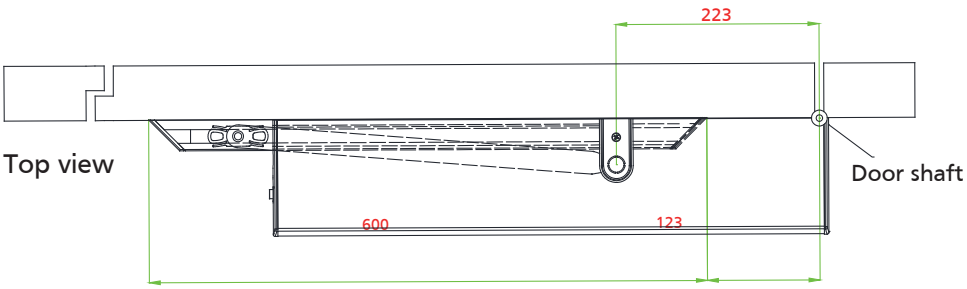
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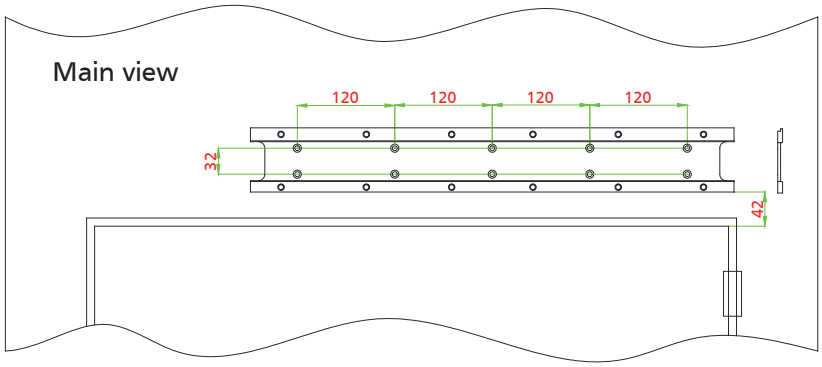








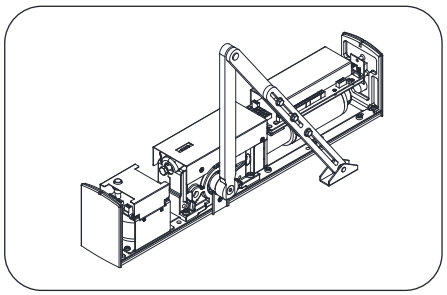
Bottom plate installation

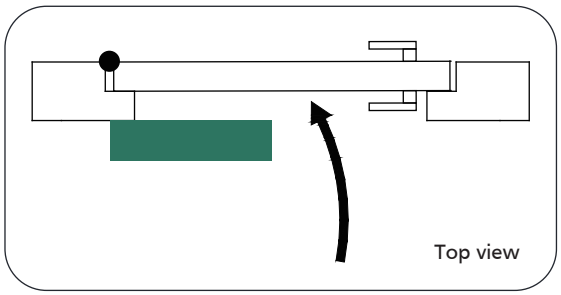


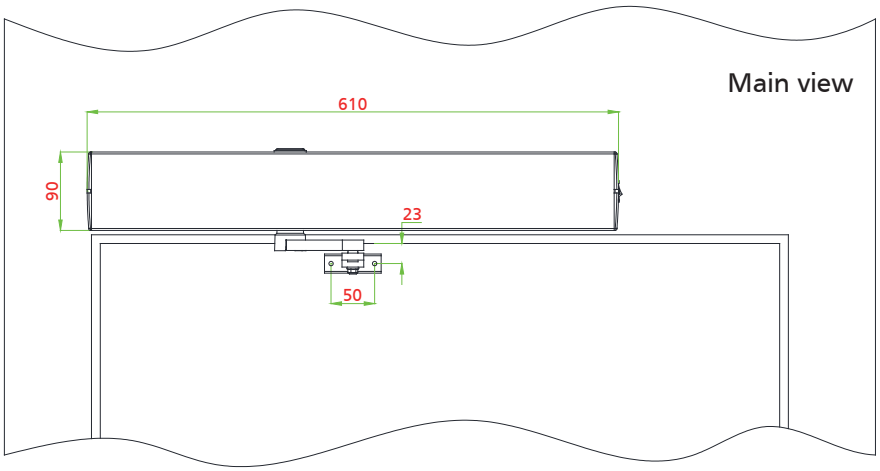
AUTOMATIC DOOR CLOSER FOR SWING DOORS

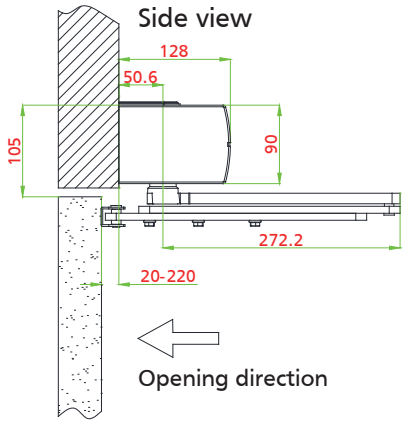
Installation (Push Arm)

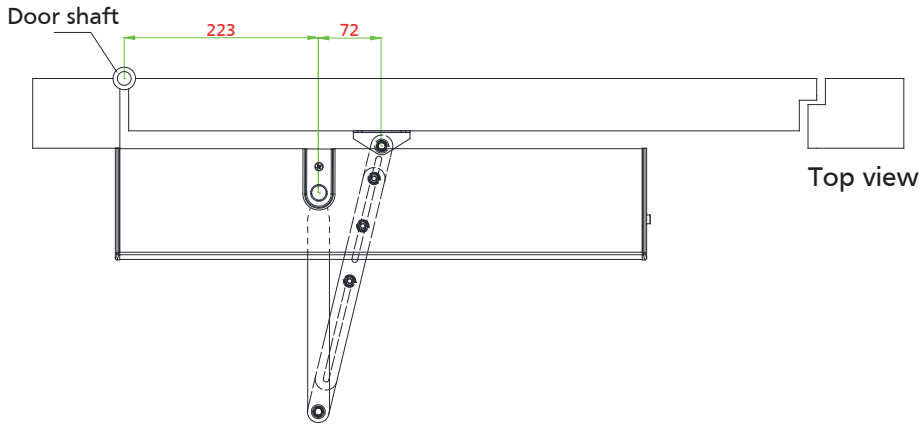
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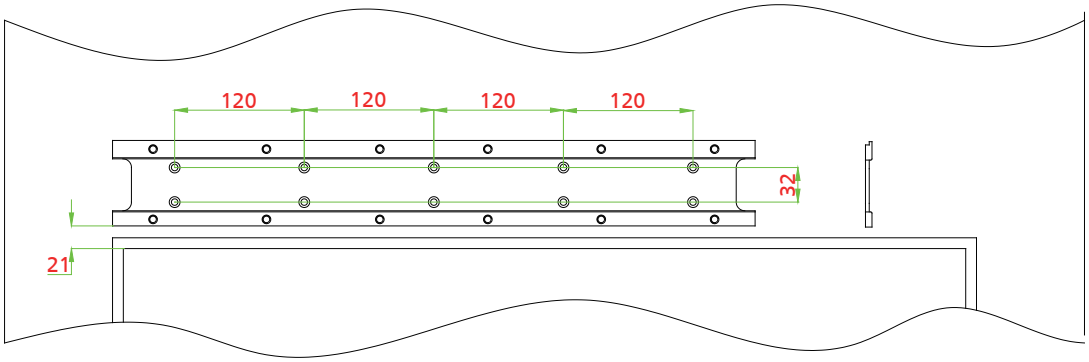




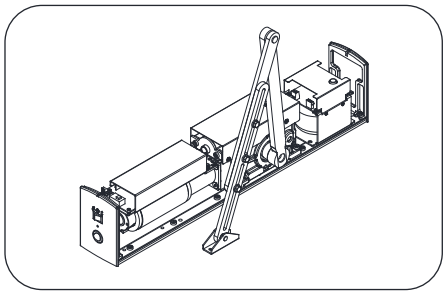


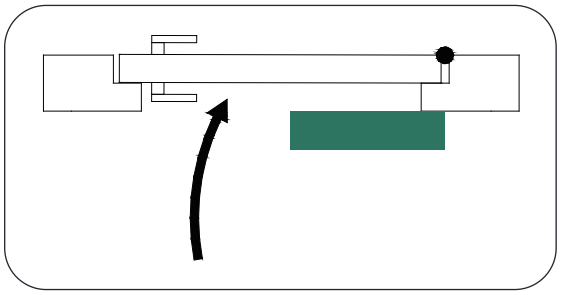


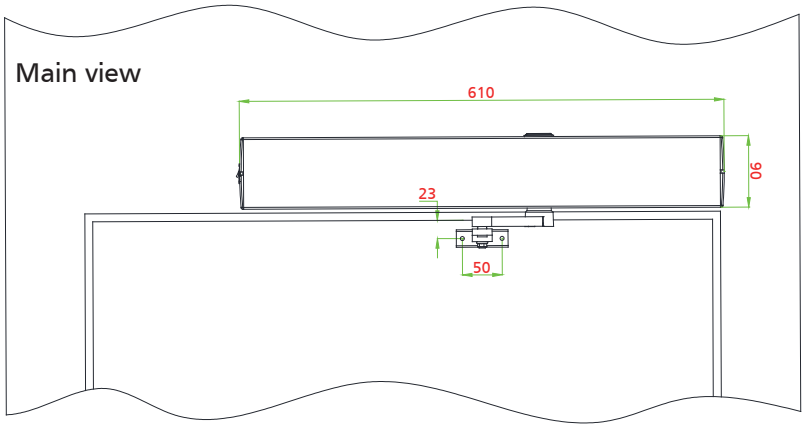
Bottom plate installation

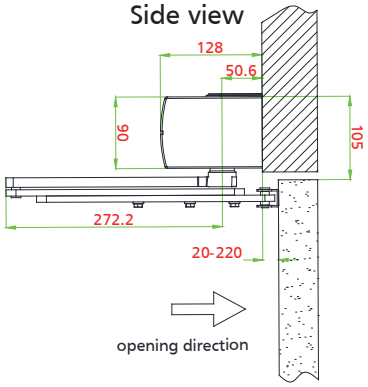


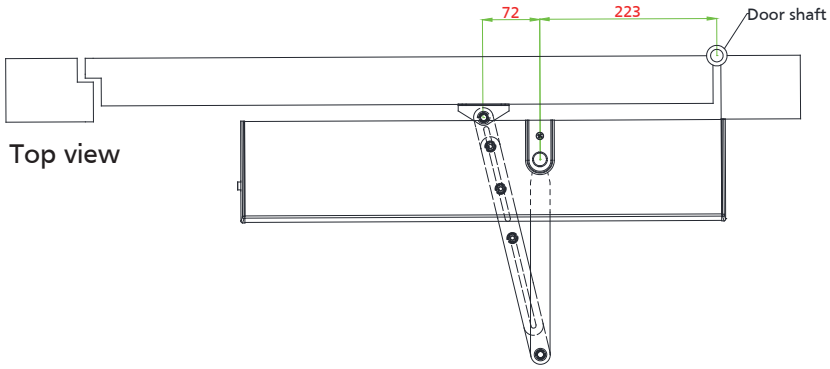
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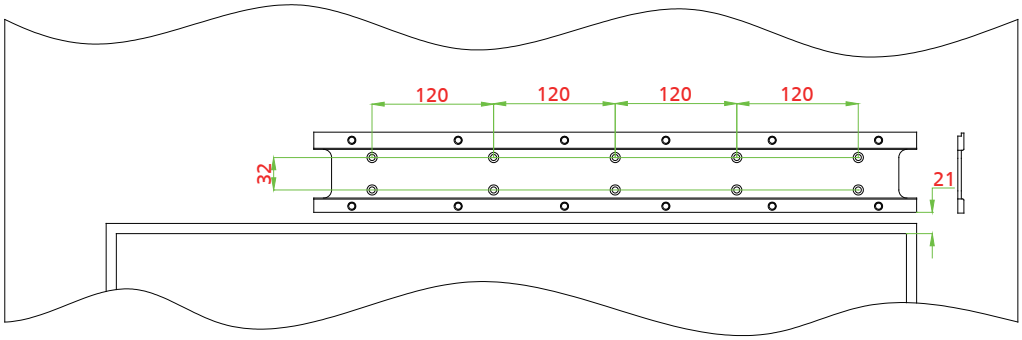








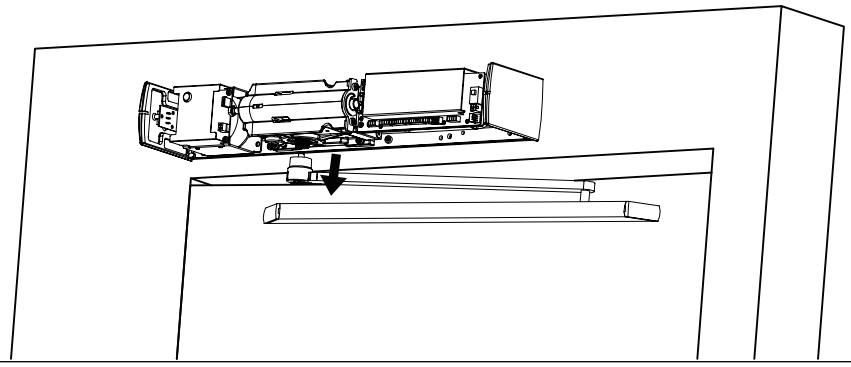
Bottom plate installation



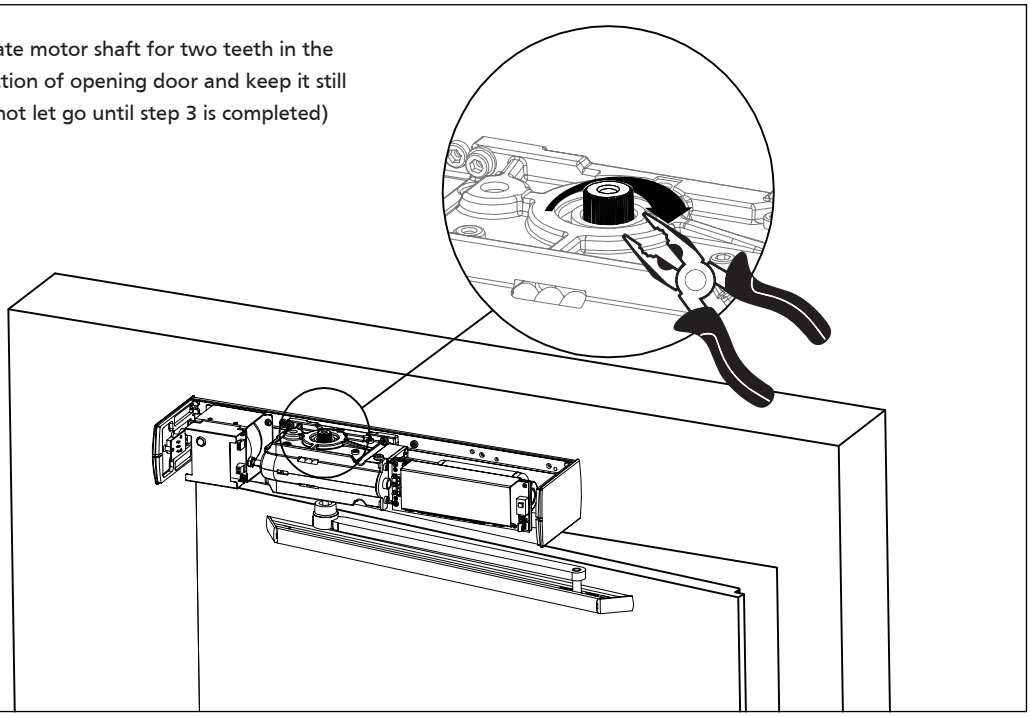
Product Adjustment

If the door panel still cannot be closed completely after increasing the torsion of the spring, it needs to be adjusted according to the following methods

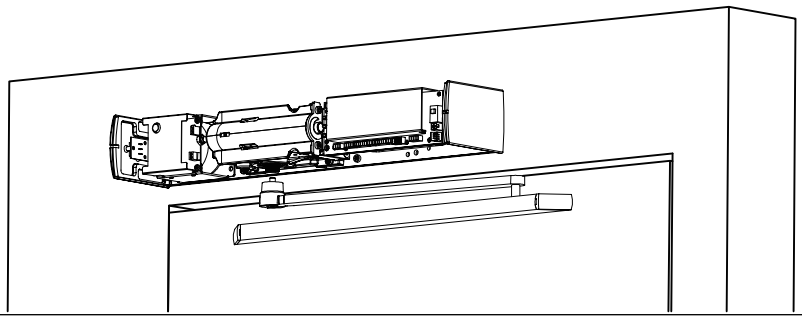
1. Detach the extension from the motor



2. Rotate motor shaft for two teeth in the direction of opening door and keep it still (do not let go until step 3 is completed)



3. Closed the door, and fix the extension with motor.



Note: After installation and debugging of the two doors, Set Pn27 of the master door's controller to 03, And Set Pn27 of Slave door's controller to 04

Adjustment step before power on

1. Remove obstacles in the running track of the door.
2. Ensure the stopper has been installed at the right position.
3. Open the door to 90 degrees, and ensure the door moving smoothly.
4. Ensure door can close slowly from full open position.
5. Ensure door power supply meet requests

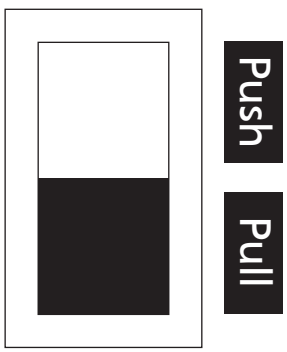
Note: If the door panel cannot be closed completely, adjust the spring force adjustment screw clockwise to increase the torque; If the door panel still cannot be closed after the spring torque is increased, please refer to the adjustment method on Page 13.

Self-learning steps

1. Turn on power switch, the indicator on power supply will be lighting.
2. The controller start to self-test.
3. Display Fn00 to F99 parameter initialization.
4. Master and slave connection self-testing (Double open mode).
5. Motor direction and encoder signal self-testing.
6. Door slowing moving to closed position.
7. Showing"CXX": Self-learning finished.

Attention

1. Obstacles not allowed during the door running track.
2. Turn off the power immediately if the door is out of control.
3. Push and pull bar's setting must be correct



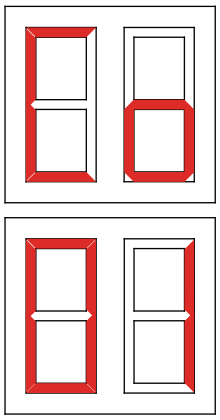
Parameter Setting

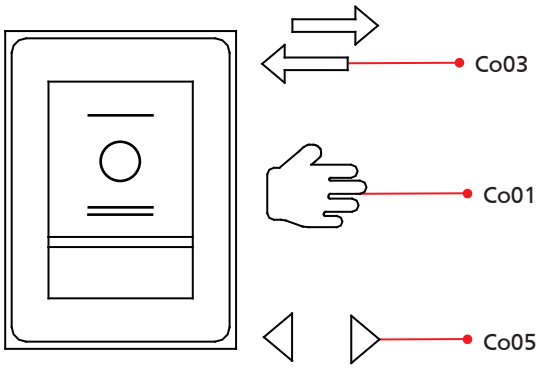
Parameter setting steps

A. Basic Parameter: There is a setting and display panel on the main control board for adjusting the operating parameters of the door and displaying the error code
Note:Total 35 items of parameter can be adjusted on controller

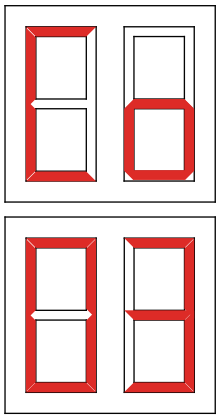
B. Mode selection:

1. Press mode select switch to Manual mode

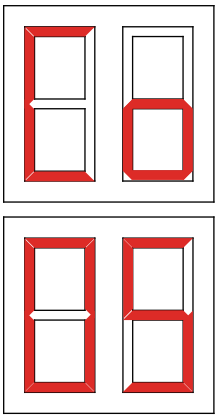




2. Press mode select switch to Automatic mode

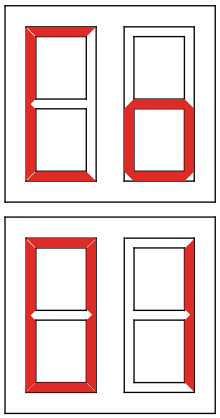


3. Press mode select switch to Always Open mode



C、 Parameter adjustment

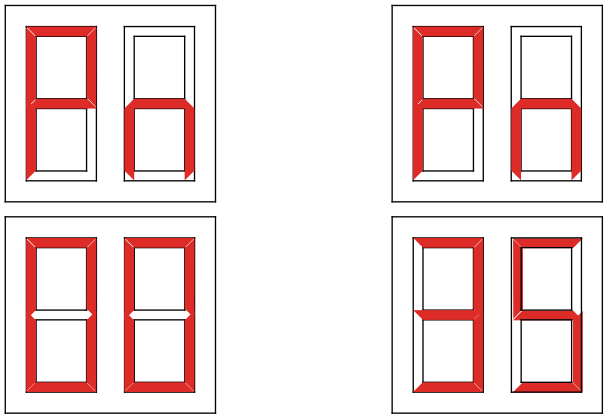
1. Parameter adjustment must under Manual mode



2. Keep pressing setting button 3 seconds

3. Enter the program selection after controller display Pn00

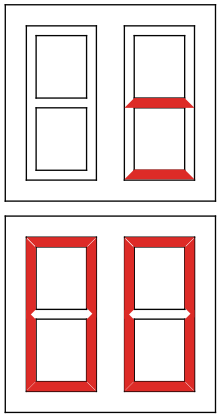
4. Press "+" or "-" button to select the program code（value from 00~35）



5. Press setting button to enter the value adjustment.

6. Press "+" or "-" button to adjust the value of program code.

(Min and Max value is limited by software)



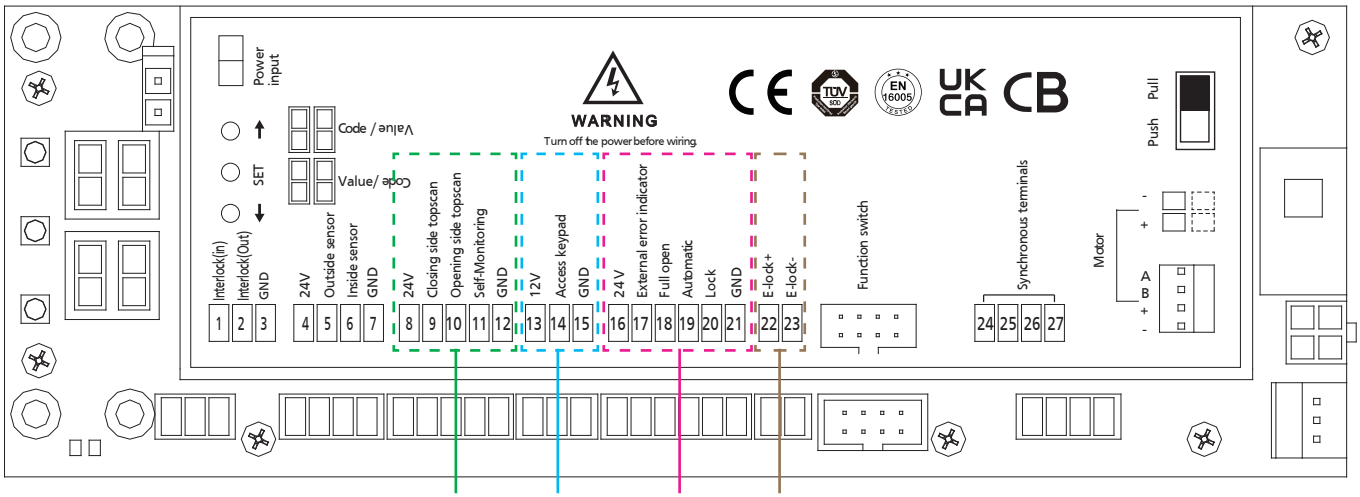
7. After pressing the set bottom, the value is saved, and back to the code selecting.

8. Continue step 4 to step7, adjust the code value as customer request.

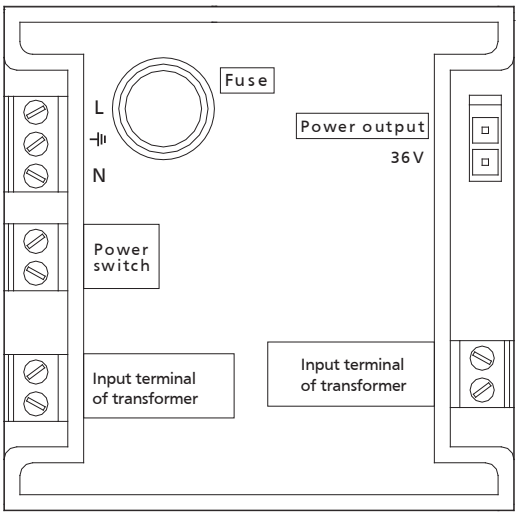
9. After the function parameter setting is completed, it is necessary to return to the interface of "FN00" and then press the "SET" button to exit the parameter setting (Or stopping for 20 seconds at the interface of any parameter adjustment will automatically exit the parameter setting)

AUTOMATIC DOOR CLOSER FOR SWING DOORS

Terminal Information



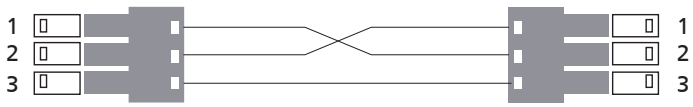
Top scan sensor | Keypad | Wireless Switch | Electric Release



1	Interlock(in)
2	Interlock(Out)
3	GND
4	24V
5	Outside sensor
6	Inside sesnsor
7	GND
8	24V
9	Closing side topscan
10	Opening side topscan
11	Sel f-test signal
12	GND
13	12V
14	Card reader
15	GND

16	24V
17	Error feedback output
18	Full open
19	Automatic
20	Lock
21	GND
22	E-lock+
23	E-loc k-
24 25 26 27	Synch ronous signal

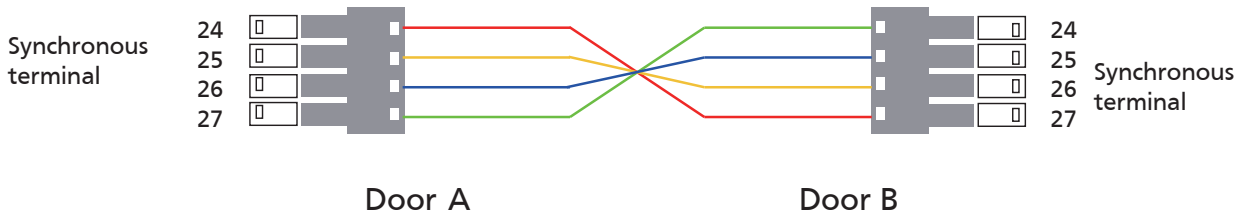
Connection of Inter-lock



Door A Door B

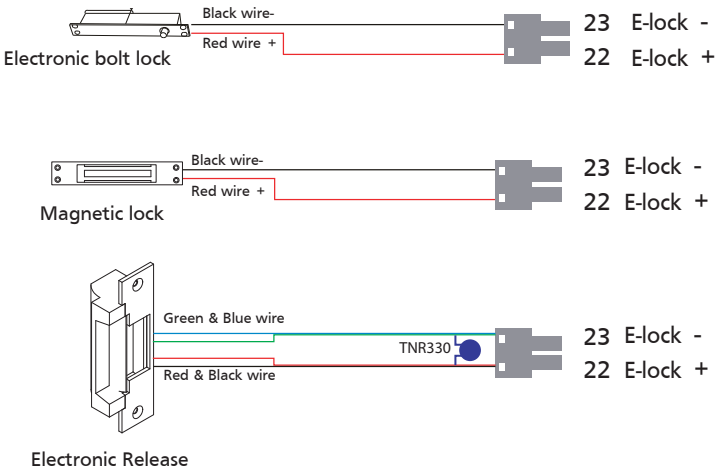
Wiring Diagram

Synchronous for double open



Note: Set Pn27 of the master door's controller to 03, And Set Pn27 of Slave door's controller to 04

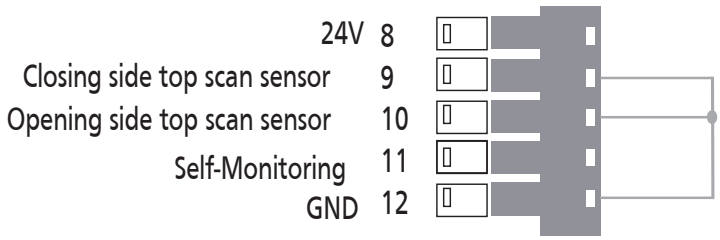
Electronic bolt lock and Magnetic lock



Note: For double opening, The Electronic bolt lock and Magnetic lock of the master door can only be connected to the controller of the master door; The Electronic bolt lock and Magnetic lock of the slave door can only be connected to the controller of the slave door.

Please reference to Electronic Magnetic Lock and Electronic Release fitting instruction for detail

Bridge connect terminal



Note: If the top scan sensor is not connected, short-circuit the opening and closing Top Scan Sensor terminal to the GND terminal.

Pn32 Parameter Values
(Controller monitoring output signal selection)

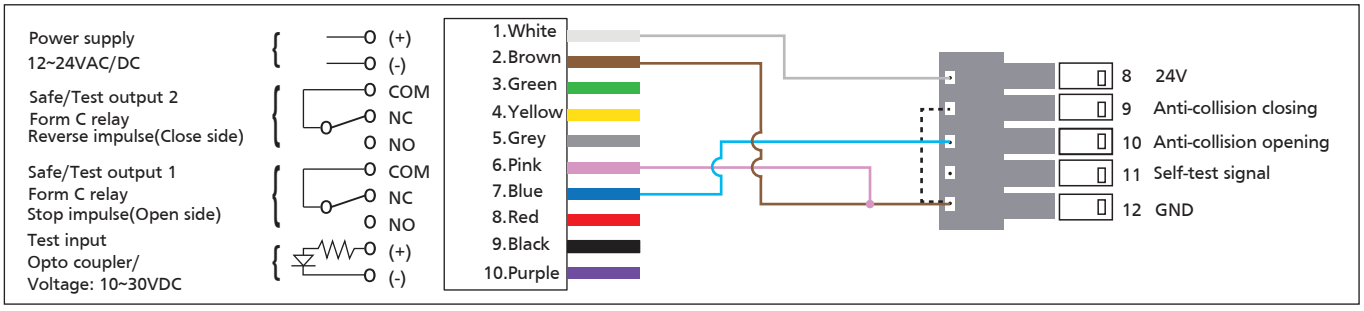
00-03	Low Level monitoring output
04-07	High Level monitoring output
00, 04	Unmonitored
01, 05	Monitor internal Top Scan sensor only (closing side)
02, 06	Monitor external top scan sensor only (opening side)
03, 07	Monitor internal and external top scan sensors (both side)

WIRING DIAGRAM

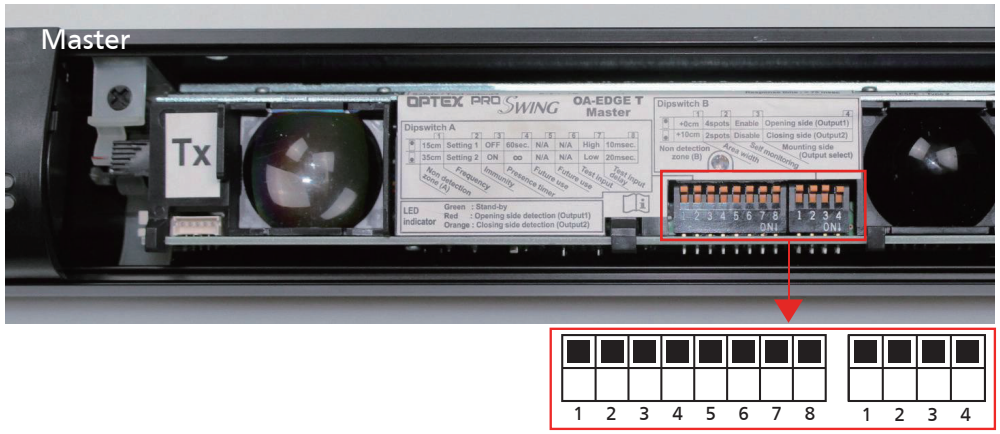
Infrared Safety Top Scan Sensor

1. Turn off monitoring function

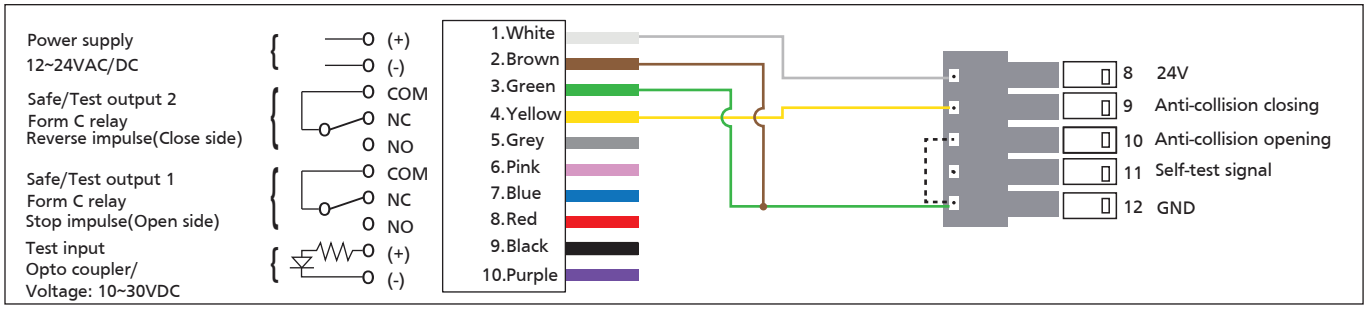
1.1 Opening side (AO.IRSS.700 Master)



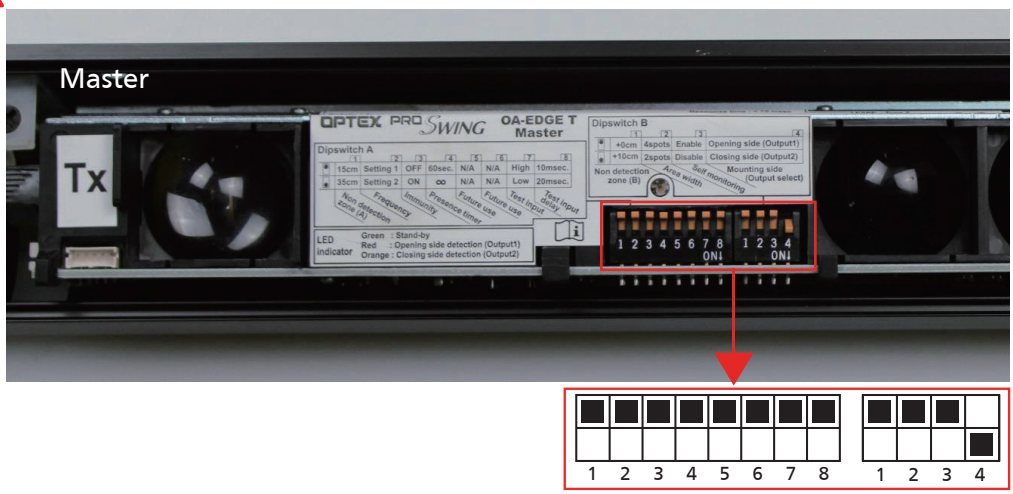
Note: When only connect top scan sensor on opening side have to short-circuit terminal 9 and 12, And Set Pn32 to 04



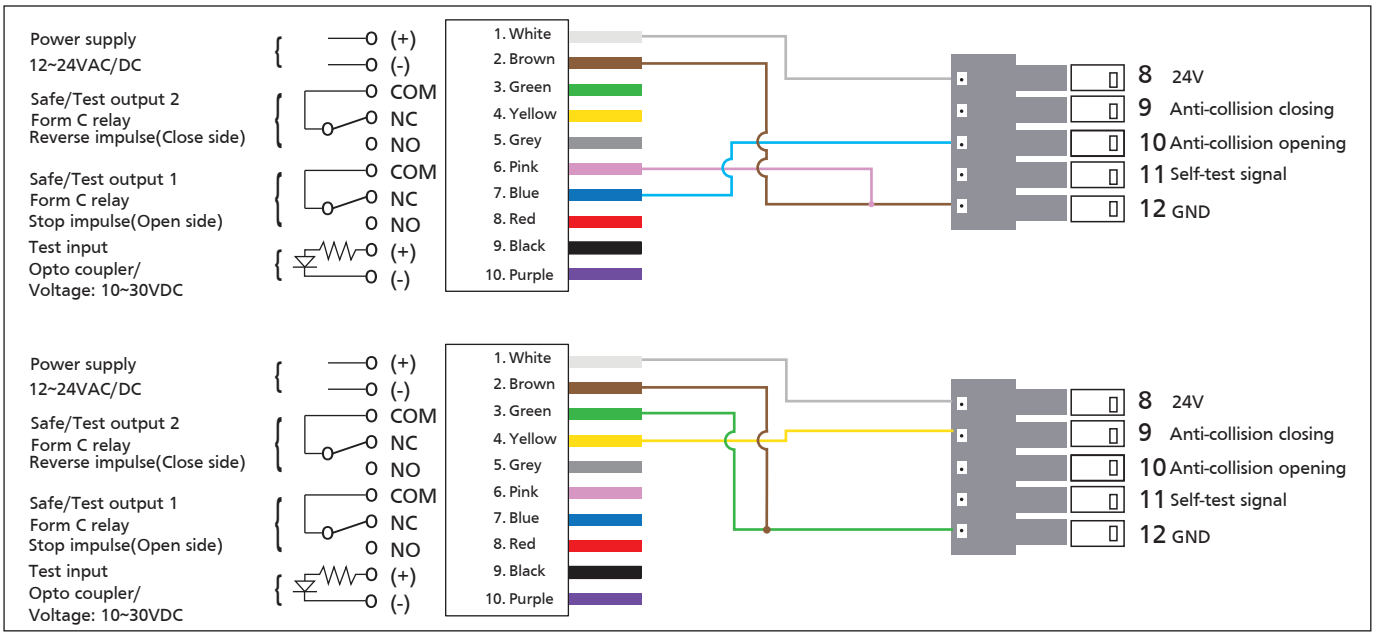
1.2 Closing side (AO.IRSS.700 Master)



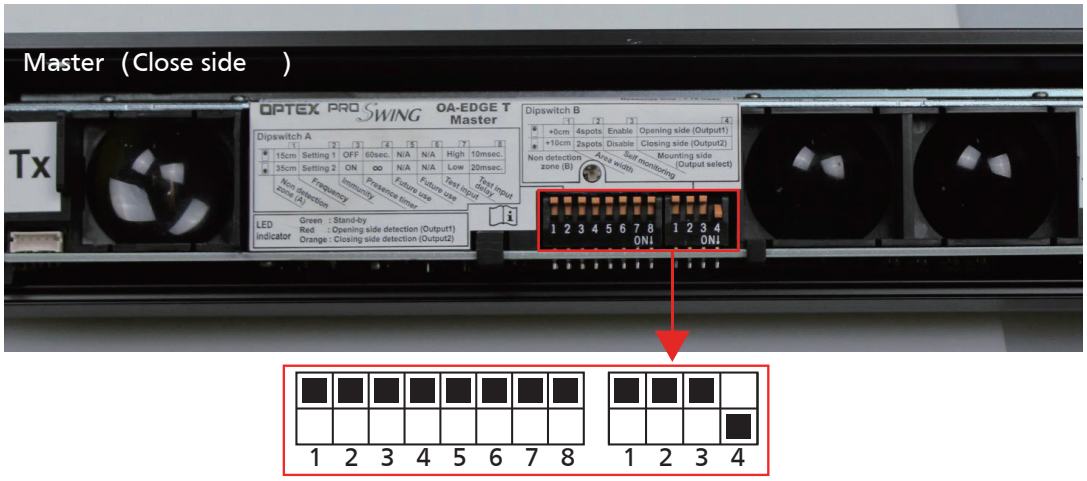
Note: When only connect top scan sensor on opening side have to short-circuit terminal 10 and 12, And Set Pn32 to 04

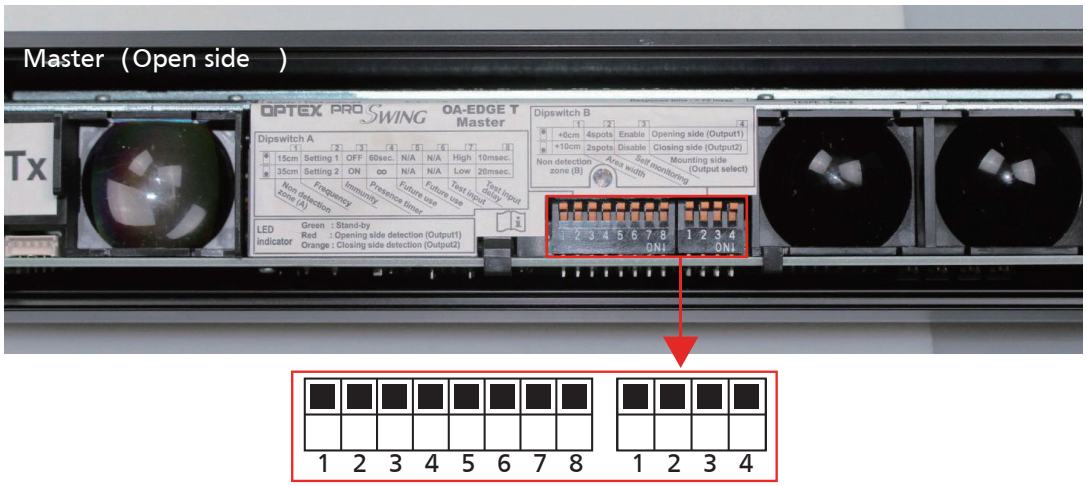


1.3 Opening and closing side (AO.IRSS.700 Master & AO.IRSS.700 Master)



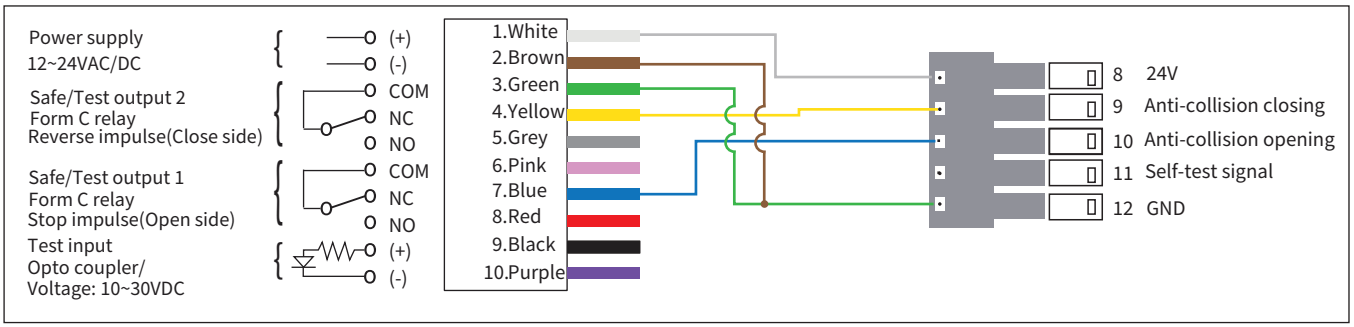
Note: Set Pn32 to 04



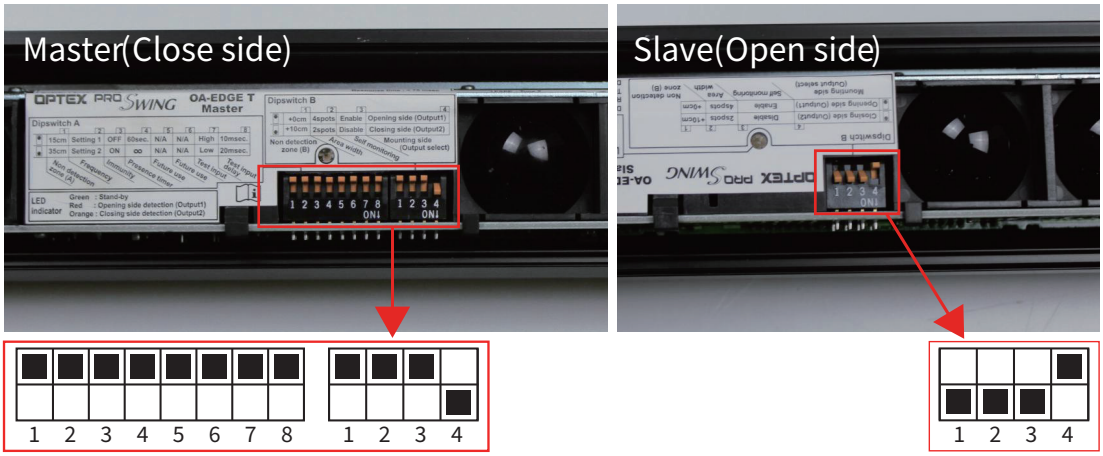


Infrared Safety Top Scan Sensor

1.4 Opening and closing side (AO.IRSS.700 Master & AO.IRSS.700 Slave)

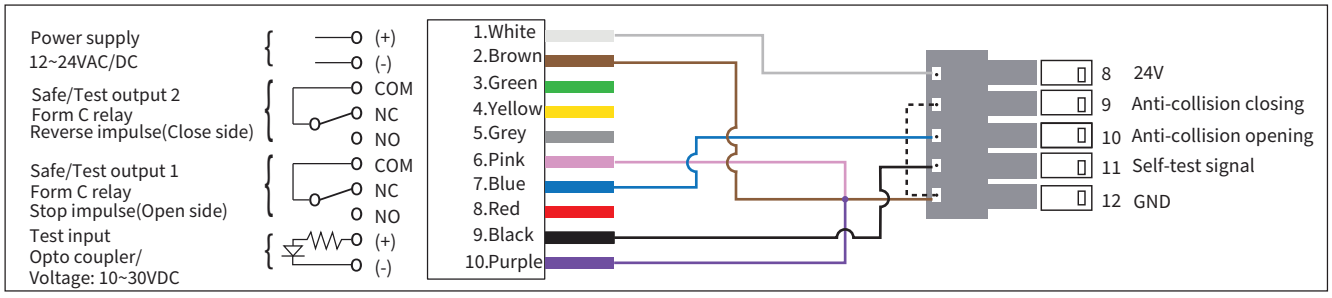


Note: Set Pn32 to 04

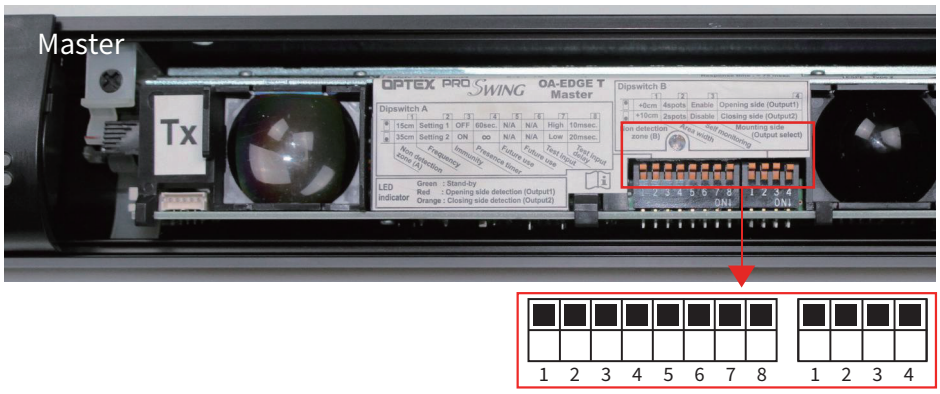


2. Turn on monitoring function

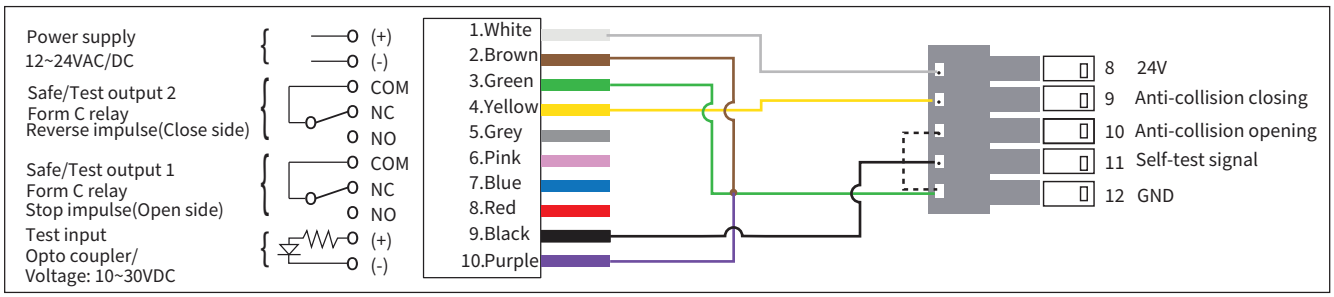
2.1 Opening side (AO.IRSS.700 Master)



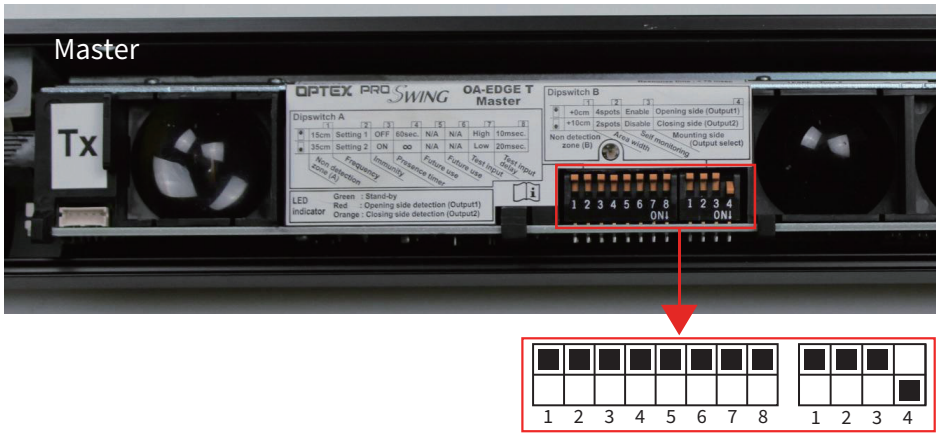
Note: When only connect top scan sensor on opening side have to short-circuit terminal 9 and 12, And Set Pn32 to 06



2.2 Closing side (AO.IRSS.700 Master)



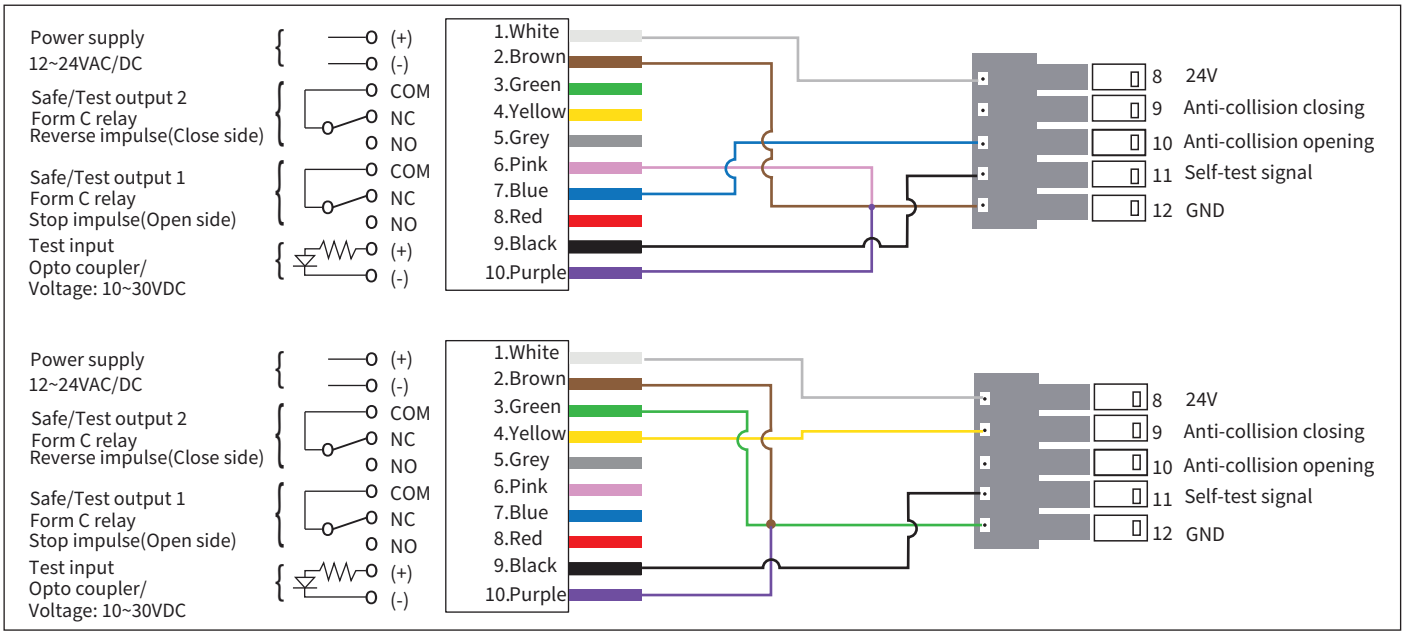
Note: When only connect top scan sensor on opening side have to short-circuit terminal 10 and 12, And Set Pn32 to 05



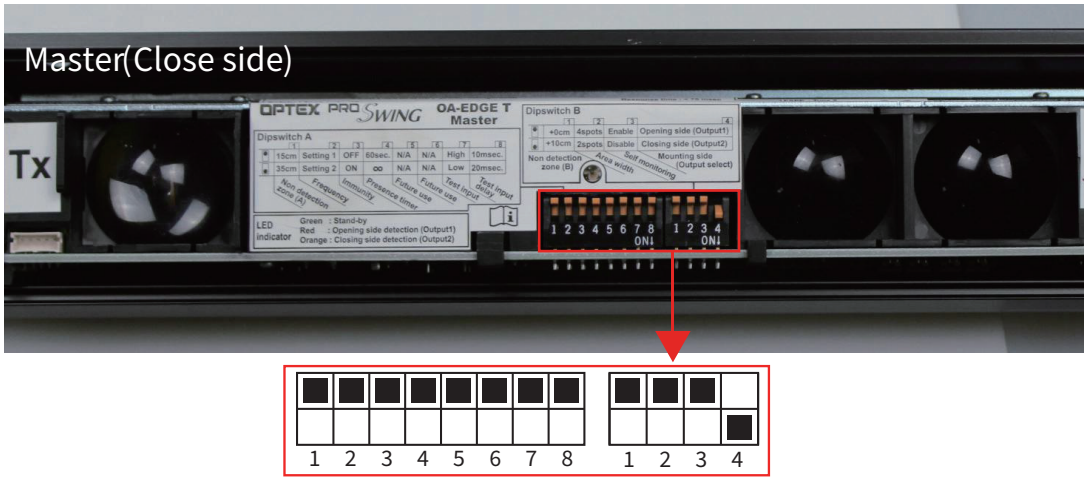
WIRING DIAGRAM

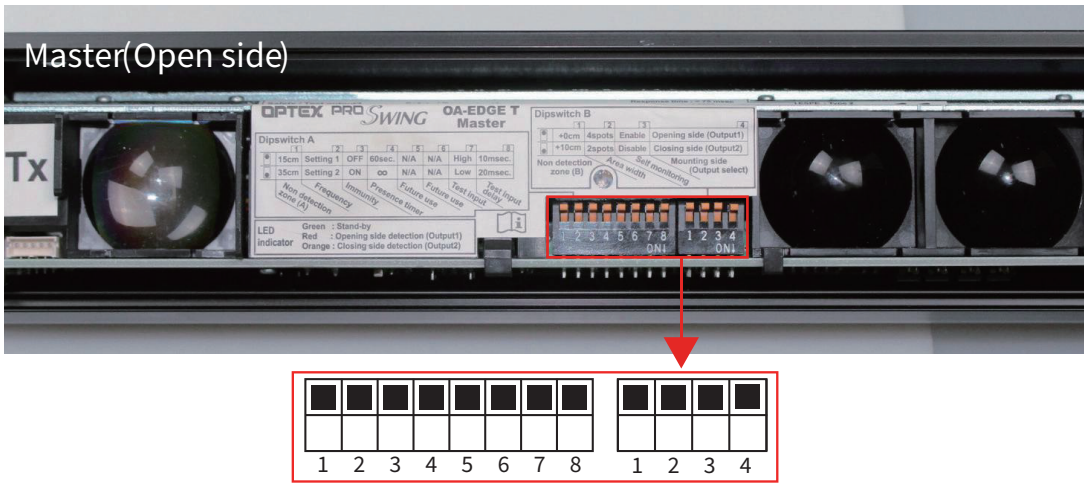
Infrared Safety Top Scan Sensor

2.3 Opening and closing side (AO.IRSS.700 Master & AO.IRSS.700 Master)



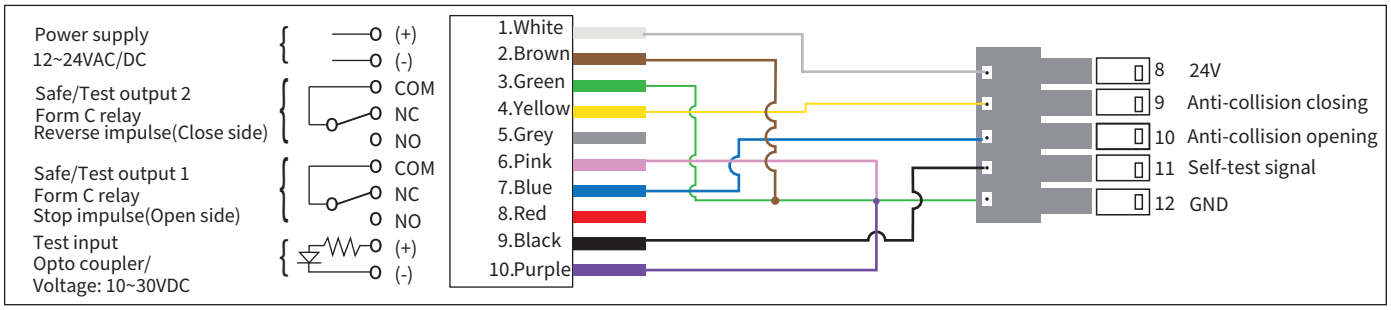
Note: Set Pn32 to 07



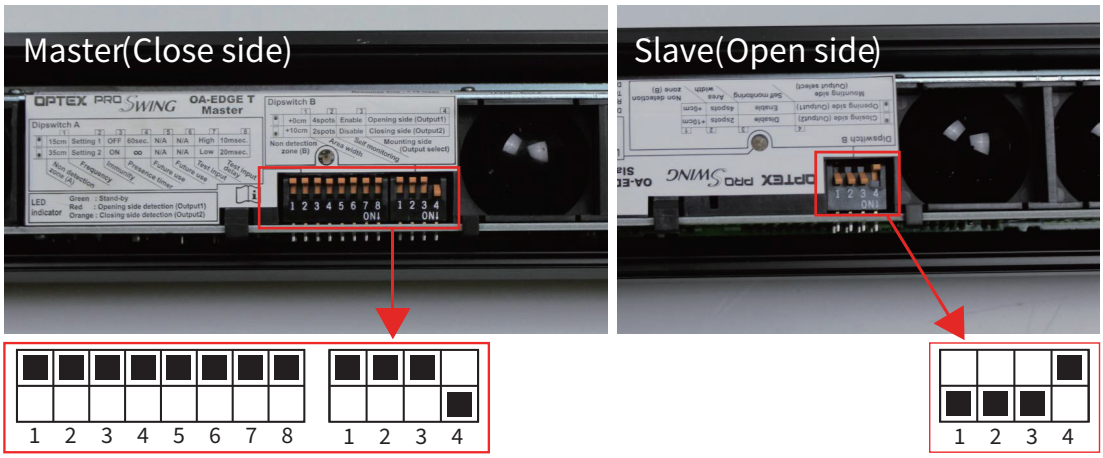


Infrared Safety Top Scan Sensor

2.4 Opening and closing side (AO.IRSS.700 Master & AO.IRSS.700 Slave)

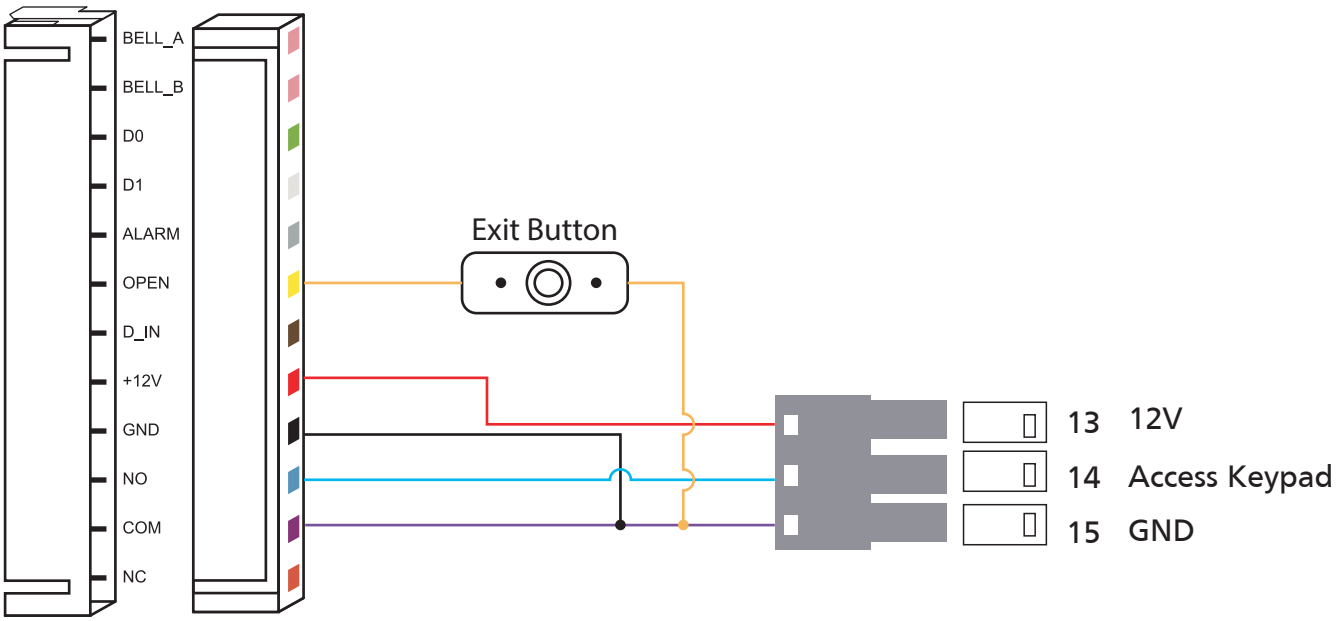


Note: Set Pn32 to 07



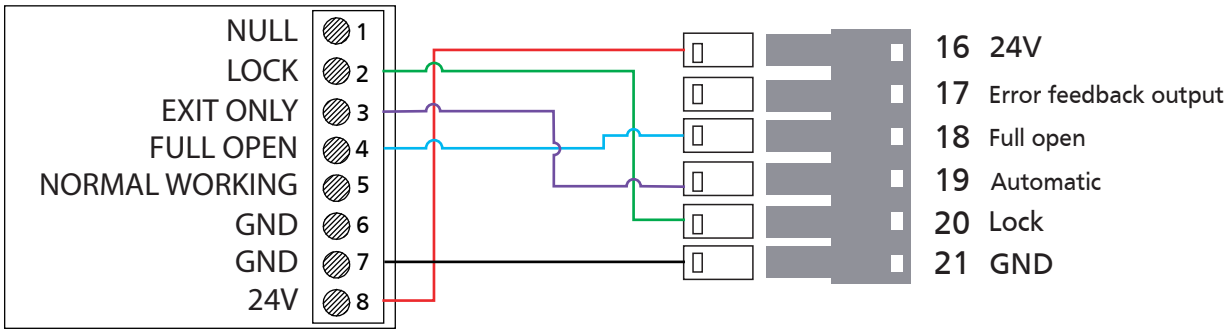
Press Button/Remote/Functional Switch/KeyPad

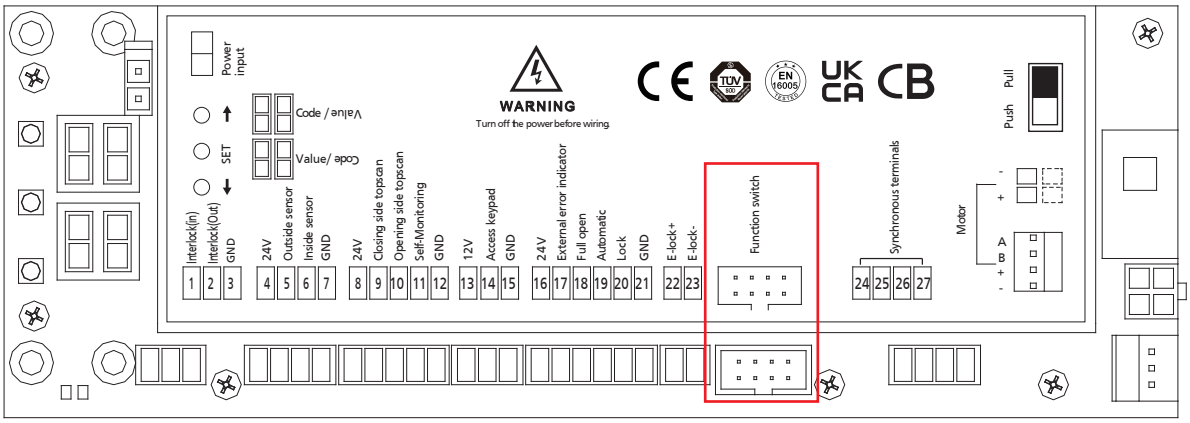
Access keypad



Note: Connecting the function keypad to the main door only.

Function switch





Note: Disconnect the Function switch cable from SW500 circuit board and switch to Auto/Co03 Mode (P.13)

Remote Button Instruction:
A: Full Open - Door keep open
B: Door close by closer spring force
C: Door close by closer motor
D: Lock - Door close and locked

Data Setting

Data setting					
Code	Function	Setting range	Default	Description	
Pn00	Quit programing				
Pn01	LED upright display/ inverted display	00, 01	00		
Pn02	Opening speed(full energy mode)	12~52	40	Degree/s	
Pn03	Closing speed(full energy mode)	10~41	30	Degree/s	
Pn04	Opening speed(Low energy mode)	10~26	20	Degree/s	
Pn05	Closing speed(Low energy mode)	8~20	15	Degree/s	
Pn06	Braking opening angle	5-45	20	5 degree to 45 degree	
Pn07	Braking closing angle	5-45	10	5 degree to 45 degree	
Pn08	Full opening angle	45-105	90	45 degree to 105 degree	
Pn09	Hold-open time	0-30	3	1=1S	
Pn10	Starting delay time	0-7	4	1=0.3S (Single open: Starting delay time, Double open: Setting "Starting delay time" on Master door; Setting "Interval time between the opening of the two doors" on Slave door)	
Pn11	Locking delay time	0-7	4	1=0.3S	
Pn12	Locking type	00, 01	00	00: active to lock 01: automatic lock when closed	
Pn13	Push and go function	00, 01	00	00: not working; 01: working	
Pn14	Holding force(closed)	01-15	05	0-7.5KGS	
Pn15	Closing force	15-30	16	The force to keep the door closed when door open by wind.	
Pn16	Anti-clamp sensitivity when opening	02-37	10	1=0.04S	
Pn17	Anti-clamp sensitivity when closing	02-25	12	1=0.04S	
Pn18	Working mode	00-01	00	00:Full energy 01: Low energy	R:Change this data and restart the controller
Pn19	Opening force(Low energy mode)	11-32	18	2~8KG	
Pn20	Closing force(Low energy mode)	02-06	02	2~5KG	
Pn21	Opening force(Full energy mode)	18-40	35	4~18KG	
Pn22	Closing force(Full energy mode)	06-16	08	4~12KG	
Pn23	Wind stack mode (The motor working mode when door open by wind)	00, 01, 02	00	00: door closed and keep 2.5s, then motor stop working 01: door closed, then motor stop working immediately 02: close at the setting angle, then motor stop working	
Pn24	Limited angle(when the door open by wind and the opening angle is bigger then limited angle,motor will start to close door)	01-45	5	1=1 degree	
Pn25	Setting angle(the angle when door closing at this position the motor stop working)	01-20	2	1=1 degree	
Pn26	Wind stack mode	00, 01	00	00：not working; 01：working	R:Change this data and restart the controller
Pn27	Master/slave door	00-04	00	00：Auto learning(master)；01：Auto learning(salve)； 03：master door；04：slave door	
Pn28	The operating way at manual mode	00, 01	01	00：all terminals don't working 01：active to open, and close by spring	R:Change this data and restart the controller
Pn29	Toggle mode	00, 01	00	00：Active to open, then closing automatically 01：Active to open, active to close	Must connect to the "sensor"terminal
Pn30	Aux lock type	00, 03	00	00: Fail safe electronic lock 01: Fail secure electronic lock 02: Fail safe strike lock 03:Fail secure strike lock	R:Change this data and restart the controller
Pn31	Save the previous failure code	–	00	Save the previous failure code	
Pn32	Top scan setting	00-07	00	Check the details at Page 18	R:Change this data and restart the controller
Pn33	Top scan sensor, slow motion area in opening	45-106	106	To prevent an uncomplete opening cycle, the door can moving at low speed when the sensor detect the wall 00: Disabled 45-106: Adjustable 45 ° ~ 105 °, Turn this function on from the set opening angle	
Pn34	Interval time between the closing of the two doors (Setting on Master door)	00-15	05	1=0.12S	
Pn35	RESET	00, 01	00	Set Pn35=01, then go to default value	R:Change this data and restart the controller

Status & Error Indicate

AO.SD3 with LED indicator design,Will show the status of operator,service people can know the trouble and status from indicator

No.	LED display	Description	Repairing suggestion	Remark
1	Fn00	Operator self-testing waiting the door stop working	Door leaf should close at the stop position by spring.	S
2	Fn01	Operator self-testing door leaf is at the stop position.	———	S
3	Fn99	Master mode	When Pn27=00 two operators have been connected	S RESET
4	F55	Slave mode	When Pn27=01 two operators have been connected	S RESET
5	F02	Operator is checking the closing position.	The process need 1~3s	S
6	Co01	Manual mode	———	RUN S
7	Co02	One way mode	———	RUN S
8	Co03	Automatic mode	———	RUN S
9	Co04	Lock mode	———	RUN S
10	Co05	Full open mode	———	RUN S
11	Pnxx	Code no	———	RUN S
12	=xx	value	———	RUN S
13	Er01	Encode or motor connection wrong	Check terminal J10	RESET
14	Er02	Motor not working or encode not connected	Check terminal J9	RESET
15	Er03	The closed position is wrong, or operator not start working at closed position.	1. Check whether the operator start working at closed position or not 2. Check the stopper is loosen or not.	RUN
16	Er04	Opening angle is more then 100degree	———	———
17	Er05	Master/slave setting wrong.	Check setting of Pn27	RESET
18	Er06	During one working circle, the encode can't detect full information.	Encode problem	———
19	Er07	During the first second when the power on, the motor doesn't work.	Encode broken or disconnect	———
20	Er08~Er09	For future	———	———
21	Er10	Operator self-testing for 20s and can't find closed position.	1. check whether the stopper is installed 2. Check the setting of switch push and pull bar.	RESET
22	Er11	Controller has problem.	Change a new controller.	RUN
23	Er16	Self-monition top scan can't finish self-testing.(closing way)	1. Check the connection of top scan. 2. Re-start the operator.	RUN
24	Er17	Self-monition top scan can't finish self-testing.(opening way)	1. Check the connection of top scan. 2. Re-start the operator.	RUN
25	Er18~Er99	For future	———	———

RUN S: State.

RUN: Check or change at working time.

RESET: The change value will be finished after re-start.

Other Information

Commissioning (to EN 16005) – carry out on every installation:

- Carry out a risk assessment of the specific doorway (users, traffic, vulnerable persons, escape use).
- Sensor-safeguarded (full-power) operation: peak dynamic force ≤400 N where the gap to the opposing edge is under 200 mm (≤700 N for 200–500 mm, ≤1400 N over 500 mm); the force may exceed 150 N for no more than 0.75s; the static force must not exceed 150 N; and the residual force must be ≤25 N at 5s.
- Low-energy mode (no safety sensors): kinetic energy ≤1.69 J; stopping force at the main edge ≤67 N; opening time ≥3s to 80° and closing time ≥1.5 s from 10° to fully closed.
- Position and test the safety sensors (AO.IRSS.700) to cover the swing path; confirm the door stops/reverses on obstruction.
- Confirm the door self-closes and latches with the power off (spring-force adjustment).
- Complete and sign the commissioning/handover record below; leave a copy with the responsible person.

Maintenance & periodic inspection schedule

- This operator must be serviced by a competent person at regular intervals (at least annually, more often in high-traffic use). At each service: re-measure edge forces against EN 16005, test the safety sensors and obstruction response, check the self-close/latch on power-off, inspect fixings, arm and wiring, and record the visit.

Decommissioning & disposal (WEEE)

- At end of life, isolate and remove the operator and dispose of it as electrical waste (WEEE) through an authorised route. Do not dispose of in general waste.

Fire / smoke doors — doorset test evidence

- Fire and smoke doors: where this operator is fitted to a fire-resisting or smoke-control doorset, there must be valid fire test evidence for that specific doorset that covers the use of a powered operator of this type. Responsibility for holding and confirming that doorset fire test evidence rests with the doorset manufacturer/supplier. Rutland does not warrant the fire performance of the doorset.

AUTOMATIC DOOR CLOSER FOR SWING DOORS

Commissioning & Handover Checklist

Automatic swing door operator | To BS EN 16005 | Complete on every installation

1 INSTALLATION DETAILS

Site name / address	Door ref / location	
Operator model / serial no.	Customer / responsible person	
Installer name	Install date	Company

2 DOORWAY RISK ASSESSMENT

- ☐ Users identified (public / staff / mixed)
- ☐ Traffic level assessed
- ☐ Vulnerable persons (elderly, children, disabled)
- ☐ Escape route use confirmed

Hazards / notes

3 MODE SET & DOOR SETTINGS

Mode set: ☐ Full-energy (sensor guarded) ☐ Low-energy (EN 16005 low-energy limits)

Opening speed (s / deg)	Closing speed (s / deg)	Hold-open time (s)	Spring force setting

4 FORCES MEASURED AT DOOR EDGE (FORCE GAUGE)

Measurement	EN 16005 limit*	Measured	Pass / Fail	Position measured
Peak dynamic force - opening	max. 400 N	N	☐ P ☐ F	
Peak dynamic force - closing	max. 400 N	N	☐ P ☐ F	
Residual static force	max. 150 N	N	☐ P ☐ F	
Low-energy: kinetic energy (if used)	per EN 16005	J	☐ P ☐ F	

Force gauge ID	Calibration due date

** Confirm against the current edition of BS EN 16005 before sign-off.*

5 SAFETY SENSORS TESTED (AO.IRSS.700) & FUNCTION CHECKS

Check	Result
Sensors positioned to cover full swing path (opening side)	☐ Pass ☐ Fail ☐ N/A
Sensors positioned to cover full swing path (closing side)	☐ Pass ☐ Fail ☐ N/A
Door stops / reverses on obstruction - opening	☐ Pass ☐ Fail ☐ N/A
Door stops / reverses on obstruction - closing	☐ Pass ☐ Fail ☐ N/A
Power off: door self-closes and latches (spring force adjusted)	☐ Pass ☐ Fail ☐ N/A
Activation devices / signage fitted and working	☐ Pass ☐ Fail ☐ N/A

6 HANDOVER & SIGN-OFF

- ☐ User instructions / operation explained to responsible person
- ☐ Copy of this record left with responsible person

Installer name	Installer signature	Date
Customer name (print)	Customer signature	Date

Door released for use: ☐ Yes ☐ No - reason / remedial action: _____

Copies: 1 x Customer / responsible person 1 x Installer file

Notes

Enhancing **compliance** and **performance** at every door

Through our expert advice and support, we provide the peace of mind that full compliance is achieved and that life safety is assured.

RUTLAND®

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